

# Barycentric triangulation of generalized maps

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## Extended abstract

*N-dimensional generalized maps*, or *n-G-maps*, are presented in [1] and [2], for the representation of the topology of subdivisions of *n*-dimensional topological spaces, orientable or not orientable, with or without boundaries (informally, a subdivision of a topological space is a partition of this space into vertices, edges, faces, volumes, ..., i.e. into cells with dimension 0, 1, 2, 3 ...; see also the notion of *cell-tuple structure* presented in [3], which is very close to the notion of *n-G-map*). The notion of *n-G-map* is an extension of the notion of combinatorial map, defined in [4], and studied by many authors ([5], [6], [7], [8], ...). The distinction between *topology* and *embedding* of a geometric object allows to differentiate among problems which raise up in Geometric Modeling, and more generally in Computational Geometry, and sometimes allows to define a hierarchization of these problems (for instance in animation of articulated objects, for computing Voronoï diagrams : see for instance [9]).

*N-dimensional simplices* and *barycentric triangulation* of a subdivision are classical notions in algebraic topology. A 1-simplex is an edge, a 2-simplex is a triangle, a 3-simplex is a tetrahedron, ... The barycentric triangulation *T* of a subdivision *M* of an *n*-dimensional topological space is (informally) a particular decomposition of this subdivision into *n*-simplices, such that the topological spaces subjacent to *T* and *M* are homeomorphic (for a more complete definition, see [10] and [11]). We here study for *n-G-maps* the corresponding combinatorial notions, and we define :

- *simplex n-G-maps*, which make a particular class of *n-G-maps* ; important properties of simplex *n-G-maps* are presented, and we describe a method for constructing simplex *n-G-maps* ;
- the *barycentric triangulation*  $G^T$  of an *n-G-map* *G*, which is an *n-G-map* deduced from *G*, and made up by the gathering of simplex *n-G-maps*. An important result is that number of boundaries and orientability are invariant by barycentric triangulation.

I think that simplex *n-G-maps* and barycentric triangulation may simplify the study of subdivisions of topological spaces, whose topology may be defined by an *n-G-map*.

The notion of *n-G-map* is here briefly reminded (for a more complete study, see [1] and [2]).

An *n-G-map* *G* is defined by an  $(n+2)$ -tuple  $G = (B, \alpha_0, \alpha_1, \dots, \alpha_n)$ , such that (Fig. 1) :

- *B* is a finite, non empty set of *darts* ;
- for each *i*,  $0 \leq i \leq n-1$ ,  $\alpha_i$  is an involution without fixed points,  $\alpha_n$  is an involution, such that : for each *i, j*,  $0 \leq i < i+2 \leq j \leq n$ ,  $\alpha_i \alpha_j$  is an involution (i.e.  $\alpha_i \alpha_j = \alpha_j \alpha_i$ ).

An *n-G-map*  $G = (B, \alpha_0, \alpha_1, \dots, \alpha_n)$ , such that  $\alpha_n$  is without fixed points, is said *without boundaries*. For each set  $\Phi$  of permutations of *B*, let  $\langle \Phi \rangle$  be the *group* of permutations of *B* generated by  $\Phi$ . For each dart *b* of *B*,  $\langle \Phi \rangle(b) = \{\phi(b), \phi \in \langle \Phi \rangle\}$  is the *orbit* of *b* relatively to group  $\Phi$ .  $\langle \alpha_0, \alpha_1, \dots, \alpha_n \rangle(b)$  is the *connected component* of *G* incidental to *b*.

Let  $G = (B, \alpha_0, \alpha_1, \dots, \alpha_n)$  be an *n-G-map* without boundaries. The *n-G-map*  $G^*$ , *dual* of *G*, is defined by :  $G^* = (B, \alpha_n, \alpha_{n-1}, \dots, \alpha_0)$ .

An *n-map* *C* is defined by an  $(n+1)$ -tuple  $C = (B, \alpha_0, \alpha_1, \dots, \alpha_{n-1})$ , such that :

- *B* is a finite, non empty set of *darts* ;
- for each *i*,  $0 \leq i \leq n-2$ ,  $\alpha_i$  is an involution,  $\alpha_{n-1}$  is a permutation, such that : for each *i, j*,  $0 \leq i < i+2 \leq j \leq n-1$ ,  $\alpha_i \alpha_j$  is an involution.

An *n-G-map*  $G = (B, \alpha_0, \alpha_1, \dots, \alpha_n)$  without boundaries is said to be *orientable* if and only if the *n-map*  $(B, \alpha_n \alpha_0, \alpha_n \alpha_1, \dots, \alpha_n \alpha_{n-1})$  has two connected components (cf. [1] for the definition of orientability in the general case).

In order to simplify, we assume the *n-G-maps* are connected.

## 1.- Simplex $n$ -G-maps .

**Definition 1 :** Let  $G = (B, \alpha_0, \alpha_1, \dots, \alpha_{n-1})$  be an  $(n-1)$ -G-map ( $n \geq 1$ ) . Let  $b \in B$ , and let  $i, j$  be such that  $0 \leq j \leq i \leq n-1$  . We define :

$$\begin{aligned} b_0 &= b ; \\ b_1 &= b\alpha_i ; \\ b_2 &= b\alpha_{i-1}\alpha_i ; \\ &\dots \\ b_k &= b\alpha_{i-k+1}\alpha_{i-k+2}\dots\alpha_{i-1}\alpha_i ; \\ &\dots \\ b_{i-j+1} &= b\alpha_j\alpha_{j+1}\dots\alpha_{i-1}\alpha_i . \end{aligned}$$

$G$  has *property of  $(j,i)$ -disjunction* if and only if :  $\forall b \in B$  :

$$\forall k, l \ (0 \leq k, l \leq i-j+1, k \neq l) : \langle \alpha_j, \alpha_{j+1}, \dots, \alpha_{i-1} \rangle (b_k) \cap \langle \alpha_j, \alpha_{j+1}, \dots, \alpha_{i-1} \rangle (b_l) = \emptyset .$$

$G$  has *property of disjunction* if and only if  $G$  has property of  $(j,i)$ -disjunction, for all  $i, j, 0 \leq j \leq i \leq n-1$  .

$G$  has *property of  $(j,i)$ -union* if and only if :  $\forall b \in B$  :

$$\left( \cup \langle \alpha_j, \alpha_{j+1}, \dots, \alpha_{i-1} \rangle (b_k) \right)_{k=0, \dots, i-j+1} = \langle \alpha_j, \alpha_{j+1}, \dots, \alpha_{i-1} \rangle (b) .$$

$G$  has *property of union* if and only if  $G$  has property of  $(j,i)$ -union, for all  $i, j, 0 \leq j \leq i \leq n-1$  .

$G$  has *property of  $(j,i)$ -partition* (resp. *partition*) if and only if  $G$  has properties of  $(j,i)$ -disjunction (resp. disjunction) and of  $(j,i)$ -union (resp. union) (Fig. 2) .

**Definition 2 :** Let  $G = (B, \alpha_0, \alpha_1, \dots, \alpha_{n-1})$  be an  $(n-1)$ -G-map ( $n \geq 2$ ) .  $G$  is said to be *quasi-triangular* if and only if, for all  $i \ (0 \leq i \leq n-2)$  :  $(\alpha_i \alpha_{i+1})^3 = \text{identity on } B$  .

**Theorem 1 :** An  $(n-1)$ -G-map  $G \ (n \geq 1)$  has *property of partition* if and only if  $G$  has *property of  $(0, n-1)$ -disjunction* and  $G$  is *quasi-triangular* ( $n \geq 2$ ) .

**Theorem 2 :** An  $(n-1)$ -G-map  $G \ (n \geq 1)$  has *property of partition* if and only if the  $(n-1)$ -G-map  $G^*$  dual of  $G$  has *property of partition* .

**Theorem 3 :** Let  $G$  and  $G'$  be two  $(n-1)$ -G-maps, both having *property of partition* . Let  $b \in B$ , and  $b' \in B'$  . Then an isomorphism  $\Phi$  exists between  $G$  and  $G'$ , such that  $\Phi(b) = b'$  (i.e. two rooted  $n$ -G-maps having *property of partition* are isomorphic) .

**Definition 3 :** Let  $G = (B, \alpha_0, \alpha_1, \dots, \alpha_n)$  be an  $n$ -G-map ( $n \geq 2$ ) .  $G$  is a *simplex  $n$ -G-map* if and only if (Fig. 2) :

- $\alpha_n$  is the identity on  $B$  ;
- $\partial(G) = (B, \alpha_0, \alpha_1, \dots, \alpha_{n-1})$  has *property of partition* .

**Theorem 4 :** Two rooted simplex  $n$ -G-maps are isomorphic .

**Theorem 5 :** A simplex  $n$ -G-map has exactly one boundary, and is orientable .

A method for constructing simplex  $n$ -G-maps, given simplex  $(n-1)$ -G-maps, will be described in the final paper (for a more complete study, and proofs of theorems, see [12]) .

## 2.- Barycentric triangulation .

**Definition 7 :** Let  $G = (B, \alpha_0, \alpha_1, \dots, \alpha_n)$  be a connected  $n$ -G-map . Let  $i$  be such that  $1 \leq i \leq n$  . The  $n$ -G-map  $G^T = (B^T, \alpha_0^T, \alpha_1^T, \dots, \alpha_n^T)$ , called *barycentric  $i$ -triangulation of  $G$* , is defined by (Fig. 3) : to each dart  $b$  of  $B$  is associated a simplex  $i$ -G-map  $S^b = (B^b, \alpha^{b_0}, \alpha^{b_1}, \dots, \alpha^{b_i})$ , where a dart  $b^b$  is distinguished . Then :

- $B^T = (\cup B^b)_{b \in B}$  ;
- $\forall j, 0 \leq j \leq i-1$  : the restriction of  $\alpha_j^T$  to  $B^b$  is equal to  $\alpha_j^b$  ;

–  $\forall j, i+1 \leq j \leq n$ , and  $\forall b \in B$  : let  $S^b$  and  $S^{b\alpha_j}$  be the simplex  $i$ - $G$ -maps associated respectively to  $b$  and to  $b\alpha_j$  ; an isomorphism  $\phi$  exists between  $S^b$  and  $S^{b\alpha_j}$ , such that  $\phi(b^b) = (b\alpha_j)^b$  ( $\phi$  is unique) ;  $\forall b' \in B^b : b'\alpha_j^T = \phi(b')$  ;  $\forall b' \in B^{b\alpha_j} : b'\alpha_j^T = \phi^{-1}(b')$ .

–  $\alpha_i^T$  : for each dart  $b$  of  $B$ , we define :

$$b_0 = b^b ;$$

$$b_1 = b^b \alpha_{i-1}^b (= b^b \alpha_{i-1}^T) ;$$

$$b_2 = b^b \alpha_{i-2}^b \alpha_{i-1}^b (= b^b \alpha_{i-2}^T \alpha_{i-1}^T) ;$$

...

$$b_i = b^b \alpha_0^b \dots \alpha_{i-2}^b \alpha_{i-1}^b (= b^b \alpha_0^T \dots \alpha_{i-2}^T \alpha_{i-1}^T) .$$

and :

$$b'_0 = (b\alpha_i)^b ;$$

$$b'_1 = (b\alpha_{i-1})^b \alpha_{i-1}^T ;$$

$$b'_2 = (b\alpha_{i-2})^b \alpha_{i-2}^T \alpha_{i-1}^T ;$$

...

$$b'_i = (b\alpha_0)^b \alpha_0^T \dots \alpha_{i-2}^T \alpha_{i-1}^T .$$

For each  $j$  ( $0 \leq j \leq i$ ), an isomorphism  $\phi_j$  exists between  $\langle \alpha_0^T, \alpha_1^T, \dots, \alpha_{i-2}^T \rangle (b_j)$  and  $\langle \alpha_0^T, \alpha_1^T, \dots, \alpha_{i-2}^T \rangle (b'_j)$ , such that  $\phi_j(b_j) = b'_j$  ( $\phi_j$  is unique) . Let  $\Phi$  be the "product" of these isomorphisms . Then, for each dart  $b'$  of  $B^b : b'\alpha_i^T = \Phi(b')$  .

**Theorem 7 :** *The barycentric  $i$ -triangulation of an  $n$ - $G$ -map is an  $n$ - $G$ -map .*

**Theorem 8 :** *Let  $G$  and  $G'$  be two  $n$ - $G$ -maps, such that  $G$  and  $G'$  are isomorphic . Let  $G^T$  and  $G'^T$  be two  $n$ - $G$ -maps respectively deduced from  $G$  and  $G'$  by barycentric  $i$ -triangulation . Then  $G^T$  and  $G'^T$  are isomorphic .*

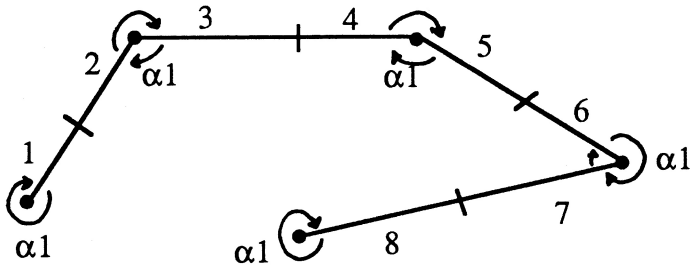
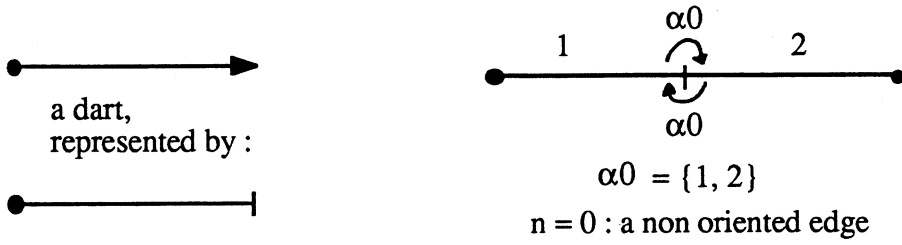
**Corollary :** *Two barycentric  $i$ -triangulations of an  $n$ - $G$ -map are isomorphic .*

**Theorem 9 :** *Number of boundaries and orientability are invariant by barycentric  $i$ -triangulation .*

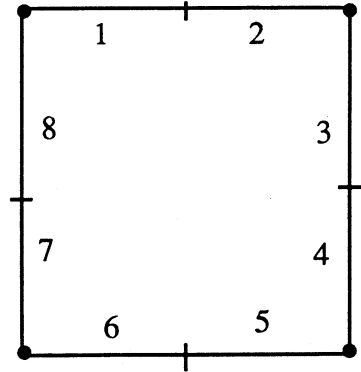
**Definition 8 :** The barycentric  $n$ -triangulation of an  $n$ - $G$ -map  $G$  is called *barycentric triangulation* of  $G$  .

## Références .

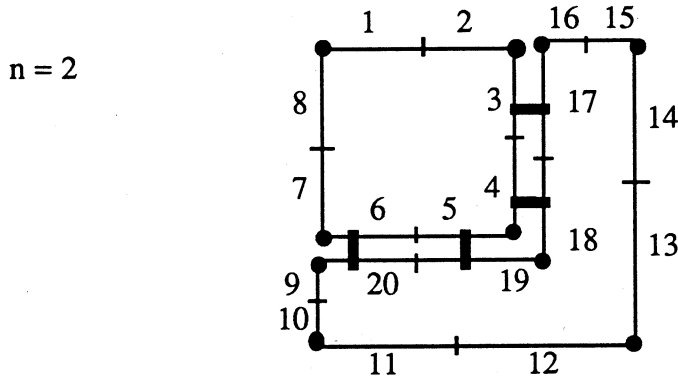
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$\alpha_0 = \{\{1,2\},\{3,4\},\{5,6\},\{7,8\}\}$   
 $\alpha_1 = \{\{1\},\{2,3\},\{4,5\},\{6,7\},\{8\}\}$   
 n = 1 : a simple elementary path



$\alpha_0 = \{\{1,2\},\{3,4\},\{5,6\},\{7,8\}\}$   
 $\alpha_1 = \{\{1,8\},\{2,3\},\{4,5\},\{6,7\}\}$   
 n = 1 : a simple elementary cycle



$\alpha_2 = \{\{1\}, \{2\}, \{3, 17\}, \{4, 18\}, \{5, 19\}, \{6, 20\}, \{7\}, \{8\}, \{9\}, \{10\}, \{11\}, \{12\}, \{13\}, \{14\}, \{15\}, \{16\}\}$

the tie  $\alpha_2$  is symbolized by a thick line  
 if  $b\alpha_2 = b$ , then  $\alpha_2$  is not represented

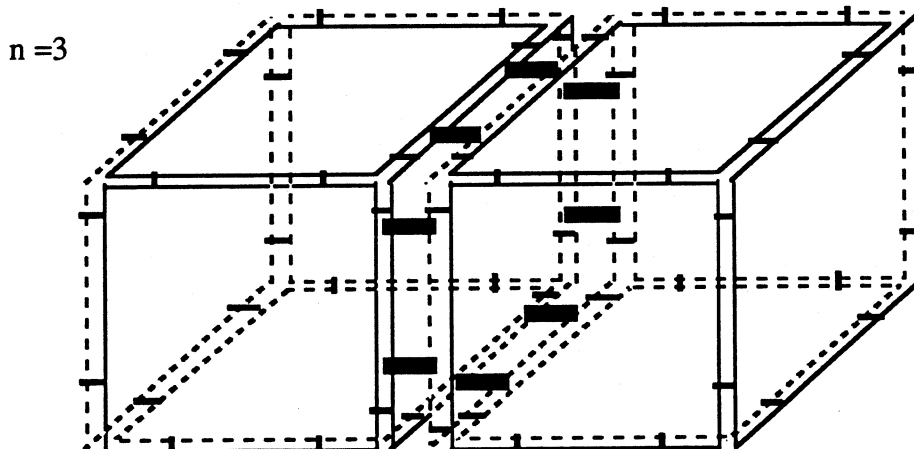


Fig. 1 : 0-, 1-, 2- and 3-G-maps .

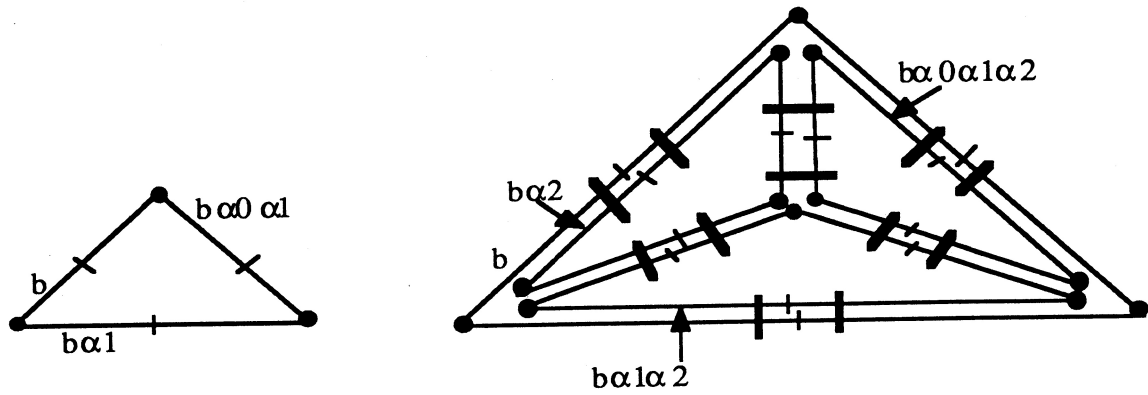


Fig. 2 : left, a 1-G-map having property of partition . Each dart  $b$ ,  $b\alpha_1$ ,  $b\alpha_0\alpha_1$  is incidental to a distinct connected component of  $(B, \alpha_0)$  . Right, a 2-G-map having property of partition. Each dart  $b$ ,  $b\alpha_2$ ,  $b\alpha_1\alpha_2$ ,  $b\alpha_0\alpha_1\alpha_2$  is incidental to a distinct connected component of  $(B, \alpha_0, \alpha_1)$  .

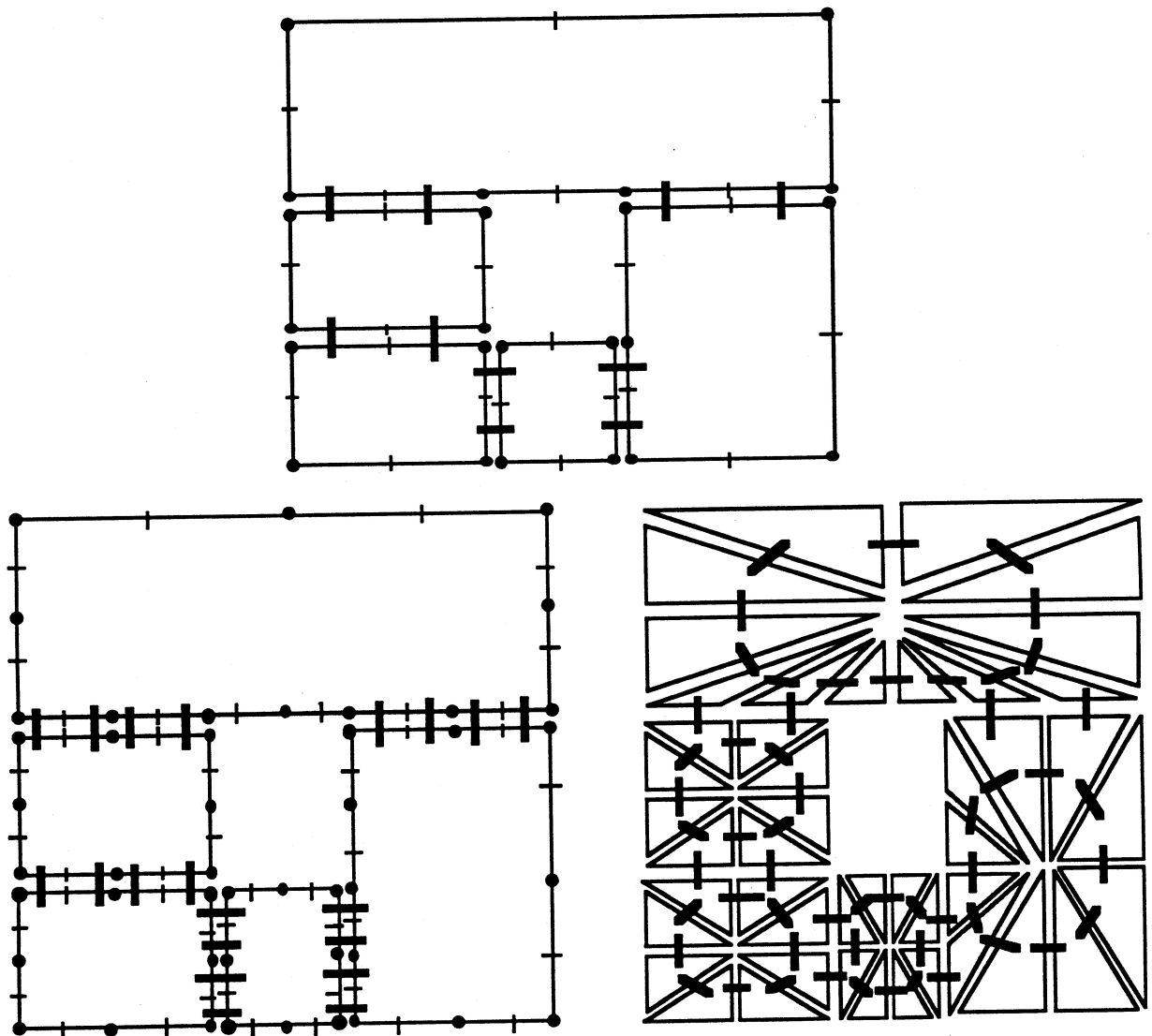


Fig. 3 : Up, a 2-G-map  $G$  is represented . Down and left, the barycentric 1-triangulation of  $G$  . Down and right, the barycentric 2-triangulation  $G^T$  of  $G$  (there is a 1-1 correspondance between the darts of  $G$  and the triangular faces of  $G^T$  ; in order to simplify the drawing of  $G^T$ , darts  $b$  and  $b\alpha^T_0$  are not distinguished) .