

# ORDER MODELS FOR MOTION IN THREE-SPACE

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## Abstract

To each member  $C_i$  of a family  $C_1, C_2, \dots$  of sets in  $R^n$  assign a direction  $d_i$  of motion. Each of these sets may represent a robot supplied with a direction of motion  $d_i$  along which it may be moved with some velocity to separate it from the others without collision. Say that  $C_j$  *obstructs*  $C_i$  if there is a point  $p_i$  in  $C_i$  and a line from  $p_i$  parallel to  $d_i$  which intersects  $C_j$ . More generally,  $C_j$  *blocks*  $C_i$ , write  $C_i < C_j$ , if there is a sequence  $C_i = C_1, C_2, \dots, C_m = C_j$  such that  $C_k$  obstructs  $C_{k+1}$ , for each  $k = 2, 3, \dots, m$ . This relation  $<$ , called a *blocking* relation, induces a (strict) order on the family of sets in  $R^n$ , as long as  $<$  contains no directed cycles (that is,  $<$  is antisymmetric). In contrast to its two-dimensional analogue [Guibas and Yao (1980), cf. Rival and Urrutia (1988)], there are families of closed convex sets in  $R^3$  for which any assignment of directions, one to each set, induces a directed cycle, whence cannot be ordered at all [cf. Dawson (1984)].

On the other hand, an ordered set  $P$  is *representable* in  $R^n$  if there is such a collection of sets in  $R^n$  whose blocking relation is the same as  $P$ . We have shown elsewhere that there are ordered sets that are not representable in  $R^2$  using only closed convex sets [Rival and Urrutia (1988)].

**THEOREM 1.** *Every ordered set is representable in  $R^3$ .*

An ordered set  $P$  has a *d-directional representation* in  $R^n$  if it is representable in  $R^3$  using at most  $d$  directions. We have shown that there is a correspondence between one-directional representations in  $R^2$  and planar embeddings of planar lattices [Rival and Urrutia (1988)].

**THEOREM 2.** *Not every ordered set has a one-directional representation in  $R^3$  using closed, convex sets.*

In  $R^2$ , every one-directional representation (equivalently, any planar lattice) can be modelled using just line segments as the closed convex sets and, moreover, all may be taken parallel.

**THEOREM 3.** *Any one-directional representation in  $R^3$  of a family of subtrees of a tree is a dismantlable lattices. On the other hand, there are dismantlable lattices with no one-directional representation at all in  $R^3$  using a family of subtrees of a tree.*

What is apparently too constrained in three-space becomes comfortably manageable in  $R^4$ .

**THEOREM 4.** *Every ordered set has a one-directional representation in  $R^4$  using closed convex subsets.*

## REFERENCES

- R. Dawson (1984) On removing a ball without disturbing the others, *Math. Mag.* 57, 27-30.
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