

# On 1-Segment Center Problem

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## Abstract

The location problem has recently been investigated from the computational-geometric point of view. The most fundamental problem is the *1-point-center problem*, or the *minimum enclosing circle problem*, for  $n$  demand points in the plane, which is to find a location of a point facility  $p$  so that the maximum distance from  $p$  to the demand points is minimized. Megiddo and Dyer presented an  $O(n)$  optimal time algorithm for this problem. A variation of the 1-point center problem is the *1-line-center problem*, which calls for the location of a line facility so that the maximum distance from the  $n$  given points to the line is minimized. This problem can be solved in  $\Theta(n \log n)$  time, which is shown to be optimal in the worst case under the algebraic computation tree model of Ben-Or.

The complexities of the 1-point-center and 1-line-center problems are essentially different, and thus naturally arises the following problem, called the *1-segment-center problem*: Given a set  $S$  of  $n$  points in the plane and a nonnegative constant  $L$ , locate a line segment of length  $L$  so that the maximum distance between the segment and the points in  $S$  is minimized. The distance between a point  $p$  and a segment  $l$  is the minimum distance between  $p$  and any point on  $l$ . The placement of a segment can be represented by  $(x, y, \theta)$ , where  $(x, y)$  are the coordinates of one (designated) endpoint of the segment, and  $\theta$  is the orientation of that segment with respect to the  $X$ -axis. Given a segment  $l$  of length  $L$  placed at  $\hat{p} = (x, y, \theta)$ , the locus of points equidistant from  $l$  at distance  $r$  is called a *segment disk* centered at  $\hat{p}$  of radius  $r$ , and is denoted as  $l(L, \hat{p}, r)$ .

It can be shown that there exist at most four points that determine the location of the segment and hence  $O(n^4 \log n)$  time suffices to find such a disk. However, for some restricted cases, more efficient algorithms can be obtained. For example, if the orientation  $\theta$  is fixed, the problem can be solved in  $O(n)$  time by *prune-and-search* technique.

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